

# Physics Cup – TalTech 2025

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## 1 Problem 5: Satellite Orbit

A satellite orbits a planet. At point  $A$ , its speed is  $v_1$ . At point  $B$ , its speed is  $v_2$  and its velocity vector forms a right angle with the velocity vector at point  $A$ . At point  $C$ , the velocity is exactly opposite to the velocity at point  $A$ , with a magnitude of  $v_3$ . Find the eccentricity of the orbit. Also, determine the exact numerical value of the eccentricity when  $v_1 = 1$  km/s,  $v_2 = 2$  km/s, and  $v_3 = 3$  km/s.

## 2 Facts

In this section, I will enunciate some useful geometrical facts about an elliptical orbit. Some proofs are left in the appendix section. To start with, consider an ellipse  $\Gamma$  with major axis  $a$  and minor axis  $b$  and focal points  $F_1$  and  $F_2$ . Set  $c = \sqrt{a^2 - b^2}$  and  $O$  as the center of  $\Gamma$ .

**Fact 1.** *If  $P$  is a point on  $\Gamma$  and  $Q$  and  $R$  are points on the tangent to  $\Gamma$  at  $P$  such that  $P \in \overline{QR}$ , then:*

- $2a = F_1P + F_2P$
- $\angle F_1PQ = \angle F_2PR$

**In simple terms:** The total distance from any point on the ellipse to its two focal points adds up to  $2a$ . Also, if a ray comes from one focus, hits the tangent at the point  $P$ , it will bounce off at the same angle and head towards the other focus.

**Fact 2.** *Given a tangent line  $l_1$  to  $\Gamma$  at  $P_1$ , there exist a unique different tangent line  $l_2$  at  $P_2$  such that  $l_1 \parallel l_2$ . In addition,  $\overline{P_1P_2}$  has  $O$  as midpoint.*

**Fact 3.** *The geometrical locus of all points  $P$  such that its tangents to  $\Gamma$  are perpendicular, it's a circumference  $\Omega$  of radius  $R = \sqrt{a^2 + b^2}$  center at the center of  $\Gamma$ .*

## 3 Conservation laws

The first conservation law is energy conservation, from one focus:

$$E = -\frac{GMm}{2a} = \frac{1}{2}mv^2 - \frac{GMm}{r}$$
$$v^2 = GM \left( \frac{2}{r} - \frac{1}{a} \right) \quad (1)$$

To find an expression for the angular momentum is trickier. Consider the minimum and maximum distances to the planet  $d_1 = a - c$  and  $d_2 = a + c$  with speeds  $u_1$  and  $u_2$  respectively. From here, the angular momentum density,  $h$ , is preserved, from which we can write the speed as  $u = h/d$ . Replacing this into the difference given by equation (1), we arrive at:

$$h^2 \left( \frac{1}{d_1^2} - \frac{1}{d_2^2} \right) = 2GM \left( \frac{1}{d_1} - \frac{1}{d_2} \right) \Rightarrow h^2 = 2GM \frac{d_1 d_2}{d_1 + d_2}$$

Using  $d_1 d_2 = (a + c)(a - c) = a^2 - c^2 = b^2$  and **Fact 1**, it is clear that our conserved quantity is:

$$h^2 = GM \frac{b^2}{a} \quad (2)$$

## 4 Geometrical trick

By **Fact 2** and **Fact 3**, the points  $A$ ,  $B$ ,  $C$ , and  $D$  are constructed in such a way that their tangents intersect at points  $P$ ,  $Q$ ,  $P'$ , and  $Q'$  as shown in **Figure 1**, forming the rectangle  $PQP'Q'$ . Let the angles formed by the tangent lines and the radial vectors from  $F_1$  at  $A$  and  $B$  be  $\phi$  and  $\beta$ , respectively. By using **Fact 1** and **Fact 2**, we can find the other angles shown in **Figure 1**.

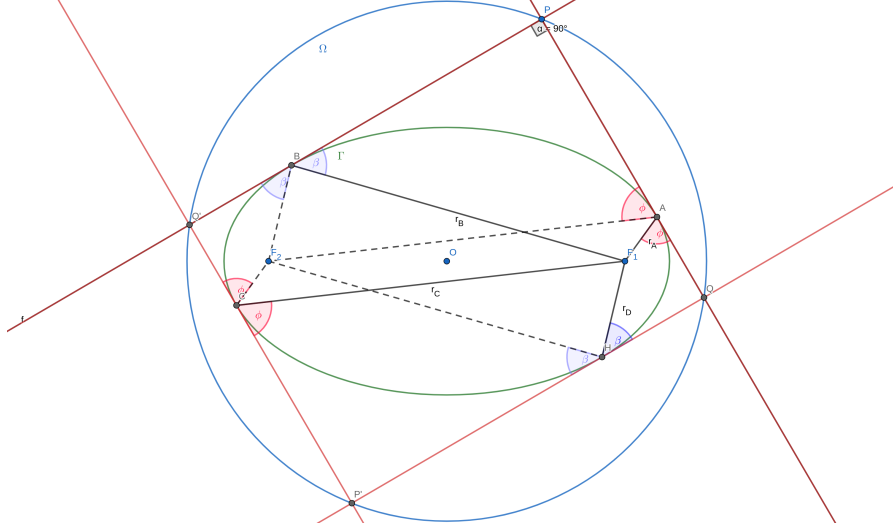


Figure 1: Geometrical construction

By using **Fact 2**,  $\overline{CA}$  and  $\overline{F_1F_2}$  have  $O$  as a midpoint, which makes  $CF_2AF_1$  a parallelogram, from which the following relations come: <sup>1</sup>

$$r_A + r_C = r_B + r_D = 2a \quad (3)$$

From this figure, it is clear that the diameter can be found as:

$$(r_A \sin \phi + r_C \sin \phi)^2 + (r_B \sin \theta + r_D \sin \theta)^2 = 4R^2 = 4(a^2 + b^2)$$

<sup>2</sup> Using (3)

$$\sin^2 \theta + \sin^2 \phi = 1 + \left(\frac{b}{a}\right)^2 \quad (4)$$

## 5 Orbital Parameters

From equations (3) and the conservation of,  $h = v_1 r_A \sin \phi = v_3 r_C \sin \phi$  it follows immediately that:

$$r_A = 2a \frac{v_3}{v_1 + v_3} \quad (5)$$

On the other hand, from energy conservation we can find the parameters  $GM$  as follows:

$$GM = \frac{v_1^2}{\left(\frac{2}{r_A} - \frac{1}{a}\right)} = \frac{v_1^2 a}{\left(\frac{v_1 + v_3}{v_3} - 1\right)} \Rightarrow GM = av_1 v_3$$

Applying energy conservation to  $B$ ,

$$\begin{aligned} v_2^2 &= av_1 v_3 \left(\frac{2}{r_B} - \frac{1}{a}\right) \\ r_B &= 2a \frac{v_1 v_3}{v_2^2 + v_1 v_3} \end{aligned} \quad (6)$$

<sup>1</sup>The same argument can be taken for  $B$  and  $D$ .

<sup>2</sup>**Fact 3** was used.

By using the equation (2) for the conservation of angular momentum density,  $h = v_1 r_A \sin \theta = v_2 r_B \sin \phi$ , and replacing (5) and (6) we arrive to:

$$\sin \theta = \left( \frac{v_2^2 + v_1 v_3}{v_2(v_1 + v_3)} \right) \sin \phi \quad (7)$$

Finally, the conservation of  $h^2$  given by (2) and  $GM = av_1 v_3$  lead us to,

$$v_1 v_3 b^2 = (v_1 r_A \sin \phi)^2$$

from (5) we finally arrive to,

$$\sin \phi^2 = \frac{(v_1 + v_3)^2}{4v_1 v_3} \left( \frac{b}{a} \right)^2 \quad (8)$$

## 6 Finding the eccentricity

We have all pieces set up to get  $e^2 = 1 - b^2/a^2$ . Therefore, replacing (7), (8) into (4),

$$2 - e^2 = \left( \frac{(v_1 + v_3)^2}{4v_1 v_3} \right) \left[ 1 + \left( \frac{v_2^2 + v_1 v_3}{v_2(v_1 + v_3)} \right)^2 \right] (1 - e^2)$$

For our sanity, the simplified expression is the following,

$$e = \sqrt{\frac{v_2^2(v_1^2 + v_2^2 + v_3^2) + v_1^2 v_3^2 - 4v_1 v_3 v_2^2}{v_2^2(v_1^2 + v_2^2 + v_3^2) + v_1^2 v_3^2}}$$

Replacing the particular case in which  $v_1 = 1$  Km/s,  $v_2 = 2$  Km/s, and  $v_3 = 3$  Km/s, we obtain:

$$e_p = \sqrt{\frac{17}{65}}$$

## Appendix: Proofs of the Facts

Assume for all the proofs that the point  $O$  is at the origin:

**Fact 1:** This is a well known fact regarding ellipses. For a complete proof, please look at it on the web.

**Lemma 1.** The tangent line at point  $P(x_0, y_0)$  has a parametric equation:

$$\frac{x_0x}{a^2} + \frac{y_0y}{b^2} = 1.$$

*Proof.* By deriving the ellipse equation, we can obtain:

$$\frac{2x}{a^2} + \frac{2y}{b^2} \frac{dy}{dx} = 0.$$

This gives the slope of the tangent at  $P(x_0, y_0)$ :

$$\left. \frac{dy}{dx} \right|_{(x_0, y_0)} = -\frac{b^2x_0}{a^2y_0}.$$

Therefore, the equation of the tangent line in point-slope form is:

$$y - y_0 = -\frac{b^2x_0}{a^2y_0}(x - x_0).$$

From where it follows immediately that:

$$\frac{x_0x}{a^2} + \frac{y_0y}{b^2} = \frac{x_0^2}{a^2} + \frac{y_0^2}{b^2} = 1.$$

□

**Fact 2:**

*Proof.* Let  $P_1(x_1, y_1)$  and  $P_2(x_2, y_2)$  be points on the ellipse where the tangents  $l_1$  and  $l_2$  meet. By **Lemma 1**, their tangent equations are:

$$\frac{x_1x}{a^2} + \frac{y_1y}{b^2} = 1 \quad \text{and} \quad \frac{x_2x}{a^2} + \frac{y_2y}{b^2} = 1.$$

For  $l_1$  and  $l_2$  to be parallel, their slopes must be equal. Which means that,

$$-\frac{b^2x_1}{a^2y_1} = -\frac{b^2x_2}{a^2y_2} \implies \frac{x_1}{y_1} = \frac{x_2}{y_2}.$$

The last equations mean that the tangents of its radial vector from the origin are equal, that is, fixing  $P_1$  our other tangent point is of the form  $(y_2, x_2) = k(x_1, y_1)$ . These equations only satisfy the ellipse equation if  $|k| = 1$ . From this, the uniqueness of  $P_2$  ( $k = -1$ ) follows immediately. In addition, it is trivial to see that for  $k = -1$ ,  $O$  is the midpoint of  $\overline{P_1P_2}$ .

□

**Fact 3:**

*The proof is certainly not mine; you can find a derivation here.* But for the sake of completeness, here it is:

*Proof.* The equation of the tangent at a point  $(u, v)$  on the ellipse is:

$$\frac{u}{a^2}x + \frac{v}{b^2}y = 1.$$

Solving for  $y$ , we obtain: <sup>3</sup>

$$y = -\frac{b^2u}{a^2v}x + \frac{b^2}{v}.$$

Using the abbreviations:

$$m = -\frac{b^2u}{a^2v}, \quad n = \frac{b^2}{v},$$

from the ellipse equation:

$$\frac{u^2}{a^2} = 1 - \frac{v^2}{b^2} = 1 - \frac{b^2}{n^2},$$

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<sup>3</sup>Here, it's assumed the tangent is non-vertical.

we get:

$$m^2 = \frac{b^4 u^2}{a^4 v^2} = \frac{1}{a^2} \frac{b^4}{v^2} \frac{u^2}{a^2} = \frac{1}{a^2} n^2 \left(1 - \frac{b^2}{n^2}\right) = \frac{n^2 - b^2}{a^2}.$$

Hence:

$$n = \pm \sqrt{m^2 a^2 + b^2} \Rightarrow y = mx \pm \sqrt{m^2 a^2 + b^2}.$$

Solving for  $(u, v)$ , we obtain the parametric representation:

$$(u, v) = \left( -\frac{ma^2}{\pm \sqrt{m^2 a^2 + b^2}}, \frac{b^2}{\pm \sqrt{m^2 a^2 + b^2}} \right).$$

For a tangent passing through  $(x_0, y_0)$ , we have:

$$y_0 = mx_0 \pm \sqrt{m^2 a^2 + b^2}.$$

Eliminating the square root leads to:

$$m^2 - \frac{2x_0 y_0}{x_0^2 - a^2} m + \frac{y_0^2 - b^2}{x_0^2 - a^2} = 0.$$

which has two solutions  $m_1, m_2$  corresponding to the two tangents passing through  $(x_0, y_0)$ . Hence, if the tangents meet at  $(x_0, y_0)$  orthogonally, the following equations hold:<sup>4</sup>

$$m_1 m_2 = -1 = \frac{y_0^2 - b^2}{x_0^2 - a^2}.$$

Rearranging, we obtain:

$$x_0^2 + y_0^2 = a^2 + b^2.$$

Which describes a circle centered at the origin with radius  $R = \sqrt{a^2 + b^2}$ . □

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<sup>4</sup>Given a quadratic equation  $x^2 + bx + c = 0$  with roots  $x_1$  and  $x_2$ , it is a well-known fact that  $x_1 x_2 = c$ .