

Physics Cup 2021 - Problem 2

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Without loss of generality, let our comet's orbit be the following ellipse, with central body located at $(e, 0)$. Note that e is the eccentricity.

$$x^2 + \frac{y^2}{1 - e^2} = 1 \quad (1)$$

Denote the points of velocities \vec{v}_1, \vec{v}_2 by subscripts 2 and 1, respectively, reflecting that symmetry argument and the location of central body permits us to locate the points on the second and the first quadrant. Let r be the distance from the point on the ellipse to $(e, 0)$ and R be the distance to $(0, 0)$.

Using the well-known vis-viva equation, $|\vec{v}_1| = 2|\vec{v}_2|$ yields

$$\frac{8}{r_2} - \frac{2}{r_1} = 3 \quad (2)$$

Apollonius's theorem applied to the triangle made of foci and comet point gives

$$R^2 = (r - 1)^2 + (1 - e^2) \quad (3)$$

We now exploit the orthogonality of \vec{v}_1 and \vec{v}_2 .

Proposition:

$$\frac{(r_1 - 1)}{\sqrt{e^2 - (r_1 - 1)^2}} \frac{(r_2 - 1)}{\sqrt{e^2 - (r_2 - 1)^2}} = -\frac{1}{1 - e^2} \quad (4)$$

Proof:

First note that for our equation of ellipse, slope of the tangent line at (x_i, y_i) on the ellipse is $-(1 - e^2) \frac{x_i}{y_i}$.

Orthogonality of \vec{v}_1 and \vec{v}_2 gives

$$\left(-(1 - e^2) \frac{x_1}{y_1} \right) \left(-(1 - e^2) \frac{x_2}{y_2} \right) = -1 \quad (5)$$

Solve for the coordinates on the ellipse (1) satisfying $x^2 + y^2 = R^2$, from which we get

$$\left(\frac{x}{y} \right)^2 = \frac{(r - 1)^2}{(1 - e^2)(e^2 - (r - 1)^2)} \quad (6)$$

Substituting the expression (6) to (5) and noting $r_1 < 1 < r_2$, the proof is done.

□

For convenience, define a new variable: $l = r_1 - 1$, $l' = r_2 - 1$, which by (2) are related by

$$l' = \frac{5l + 3}{3l + 5} \quad (7)$$

Equation (4) becomes

$$\frac{l}{\sqrt{e^2 - l^2}} \frac{l'}{\sqrt{e^2 - l'^2}} = -\frac{1}{1 - e^2} \quad (8)$$

After some algebra, we can solve (8) for e^2 .

$$e^2 = \frac{l^2 + l'^2 - 2l^2 l'^2}{1 - l^2 l'^2} \quad (9)$$

Finally, using (7) and (9), we get

$$e^2 = \frac{41l^4 + 30l^3 - 32l^2 - 30l - 9}{25l^4 + 30l^3 - 30l - 25} \quad (10)$$

This is minimized at $l = -\frac{1}{3}$, giving $\frac{1}{5}$, which is valid since $-1 < l < 0$.

Thus, we find the smallest possible eccentricity.

$$e = \frac{1}{\sqrt{5}}$$

Further generalization:

We can solve the problem with the condition $|\vec{v}_1| = k|\vec{v}_2|$, where $k > 1$. $k < 1$ is also treated modulo relabeling. For $k = 1$, the answer is trivially $e = 0$ (circle).

Starting from modifying (2), we obtain the analog of (10).

$$e^2 = \frac{(k^4 + 6k^2 + 1)l^4 + 2(k^4 - 1)l^3 - 8k^2 l^2 - 2(k^4 - 1)l - (k^2 - 1)^2}{(k^2 + 1)^2 l^4 + 2(k^4 - 1)l^3 - 2(k^4 - 1)l - (k^2 + 1)^2} \quad (10^*)$$

This is minimized at $l = -\frac{k-1}{k+1}$, giving $\frac{(k-1)^2}{k^2+1}$.

Therefore, the smallest possible eccentricity is

$$e = \frac{k-1}{\sqrt{k^2+1}}$$